## Optical Odometry Engineering Notes

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Preparing for second drive experiment:

Want to add a centimeter resolution acoustic rangefinder and implement better GPS

Need a method to record serial data from the rangefinder, planning to use python.

Spec for rangefinder

height for first drive test ~ 25 cm

My best guess for mounting height by looking at vehicles is 30 to 60 cm, (1 ft to 2 ft)

3/12/2018 Able to parse a Novatel span cpt file, bestxyza, bestvela

From closer look at the way Novatel reports velocity and INS attitude, it seems that it will be better to log longitude, lattitude and altitude and to do all computations in a locally flat coordinate system with z parallel to the perpendicular (gravity vector)

3/19/2018 Adding Aquity AR700RP-8 laser rangefinder

Initial testing:

AR700 clamped to a cart apprx 9.25” above the floor

Connected through serial to usb cable, 9600 baud

On power up, laser spools data, reading is 1.235”. This must be height above 8”. This sensor is a -8 model, 8” span with minimum distance = 8”

Test this by placing spacer blocks under the beam: 8” is minimum reading = 0.

The sensor I ordered is a -16 model with a 16” span and 21” offset

Minimum measurement distance = standoff – span / 2 = 21 – 8 = 13”

Range = 13” to 29”

Note: it is now apparent that the laser beam will likely be within the footprint of the translation camera image area.

3/20/18 Developing python script to set rangefinder parameters and read data.

Got something working, able to read the serial port at 9600 baud

change baud rate to 115200 command B9

save parameter change command w1234

set sample rate to 300 Hz or roughly 2 x the camera sample rate

S = 200,000 / F = 200,000 / 300 = 667

adapt python script to sample data for a finite interval

Adapt python script to control sample rate of sensor